



Assessment of Fictitious Domain method for Linear Stability Analysis of Fluid-Structure systems

J. Moulin, J-L. Pfister, M.Carini, O.Marquet

Office National d'Etudes et de Recherches Aéronautiques,
Département Aérodynamique Fondamentale et Expérimentale

Funded by *ERC Starting Grant*

ERCOFTAC-SIG33, Siena, 19-21 June 2017

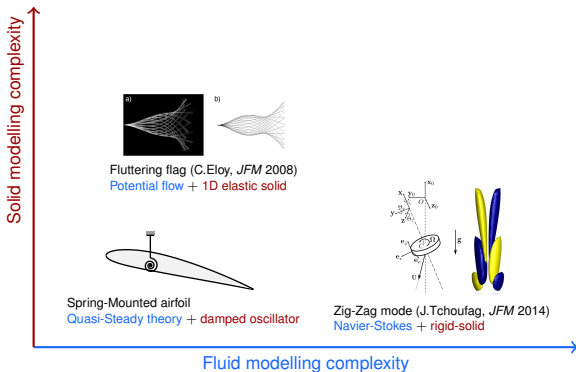


European Research Council
Established by the European Commission

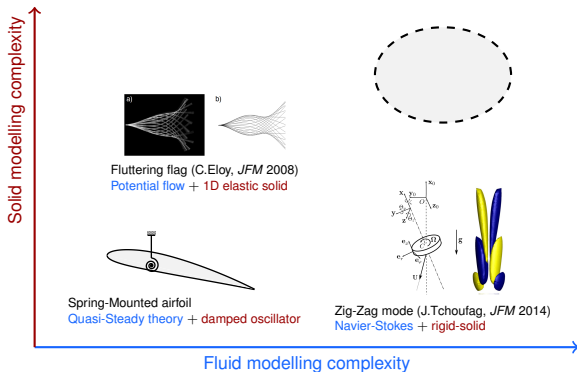
ONERA

THE FRENCH AEROSPACE LAB

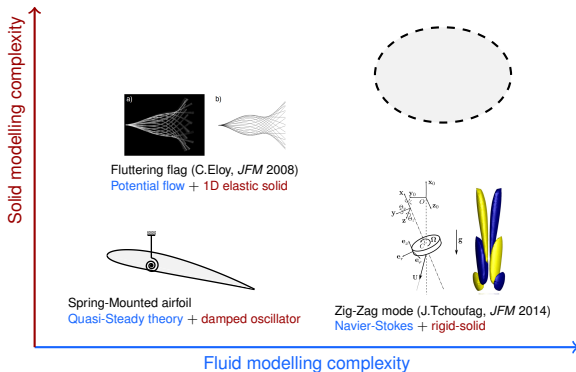
Linear Stability Analysis & FSI



Linear Stability Analysis & FSI



Linear Stability Analysis & FSI



Objective

Assess the use of **Fictitious Domain** approach for **Stability Analysis** of **FSI** systems

Plan

- 1 Introduction
- 2 Conforming vs. Non-Conforming
- 3 App.1 : VIV on rigid cylinder
- 4 App. 2 : cylinder with flexible appendice
- 5 Conclusion

Numerical frameworks for FSI

Description of the separate problems

Fluid : Eulerian description

in domain $\Omega^f(t)$

Solid : Lagrangian description

in domain Ω_0^s

Numerical frameworks for FSI

Description of the separate problems

Fluid : Eulerian description

in domain $\Omega^f(t)$

Solid : Lagrangian description

in domain Ω_0^s

Description of coupled FSI problems

Conforming methods

Arbitrary Lagrangian-Eulerian method (ALE)

(J.Donea, *Enc. Comp. Mech.* 2004)

- Artificial unknowns : mesh displacement in the **fluid region**
- Added equation : **fluid mesh movement** equation

Non-Conforming methods

Fictitious Domain method (FD)

(R.Glowinsky, *Int. J. Numer. Meth. Fluid* 1999)

- Artificial unknowns : fluid velocity in the **solid region**
- Added equation : **constraint equation** to impose the solid presence

Numerical frameworks for FSI

Description of the separate problems

Fluid : Eulerian description
in domain $\Omega^f(t)$

Solid : Lagrangian description
in domain Ω_0^s

Description of coupled FSI problems

Conforming methods (Ref.)

Arbitrary Lagrangian-Eulerian method (ALE)
(J.Donea, *Enc. Comp. Mech.* 2004)

- Artificial unknowns : mesh displacement in the **fluid region**
- Added equation : **fluid mesh movement equation**

Non-Conforming methods

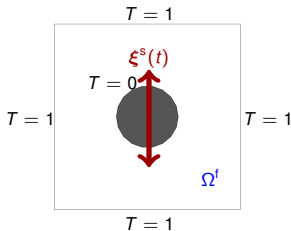
Fictitious Domain method (FD)
(R.Glowinsky, *Int. J. Numer. Meth. Fluid* 1999)

- Artificial unknowns : fluid velocity in the **solid region**
- Added equation : **constraint equation** to impose the solid presence

An illustrative example

Heat equation in a moving domain $\Omega^f(\xi^s(t))$:

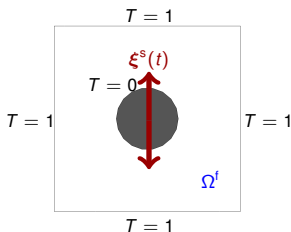
$$\Delta T = 0 \text{ in } \Omega^f(\xi^s(t))$$



An illustrative example

Heat equation in a moving domain $\Omega^f(\xi^s(t))$:

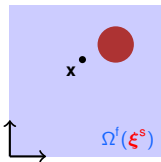
$$\Delta T = 0 \text{ in } \Omega^f(\xi^s(t))$$



- How is the fluid-structure coupling handled in ALE vs. Fictitious Domain frameworks ?

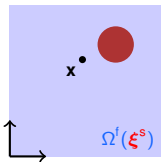
ALE formalism : an illustrative example

Current configuration



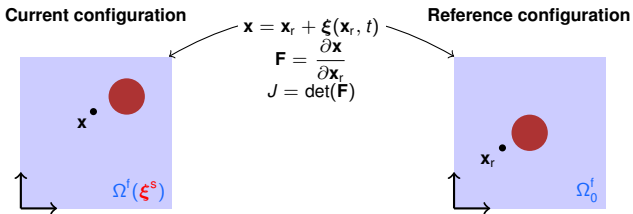
ALE formalism : an illustrative example

Current configuration



$$\int_{\Omega^t(\xi^S)} \nabla T \cdot \nabla v \, d\mathbf{x} = 0$$

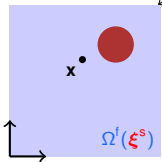
ALE formalism : an illustrative example



$$\int_{\Omega^t(\boldsymbol{\xi}^s)} \nabla T \cdot \nabla v \, d\mathbf{x} = 0$$

ALE formalism : an illustrative example

Current configuration

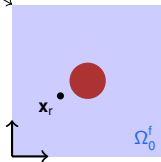


$$\mathbf{x} = \mathbf{x}_r + \boldsymbol{\xi}(\mathbf{x}_r, t)$$

$$\mathbf{F} = \frac{\partial \mathbf{x}}{\partial \mathbf{x}_r}$$

$$J = \det(\mathbf{F})$$

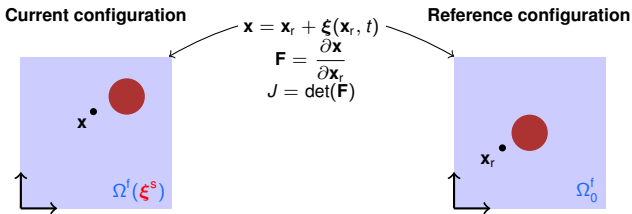
Reference configuration



$$\int_{\Omega^t(\xi^s)} \nabla T \cdot \nabla v \, d\mathbf{x} = 0$$

$$\int_{\Omega_0^t} (\mathbf{F}(\xi^s))^{-T} \nabla T \cdot (\mathbf{F}(\xi^s))^{-T} \nabla v \, J(\xi^s) \, d\mathbf{x}_r = 0$$

ALE formalism : an illustrative example

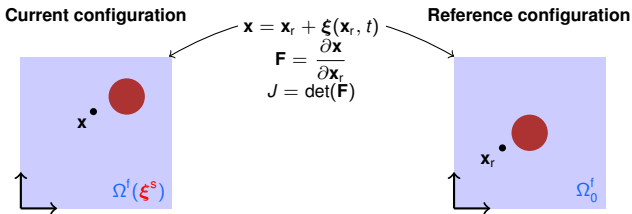


$$\int_{\Omega^f(\boldsymbol{\xi}^S)} \nabla T \cdot \nabla v \, d\mathbf{x} = 0$$

$$\int_{\Omega_0^f} (\mathbf{F}(\boldsymbol{\xi}^S))^{-T} \nabla T \cdot (\mathbf{F}(\boldsymbol{\xi}^S))^{-T} \nabla v \, J(\boldsymbol{\xi}^S) \, d\mathbf{x}_r = 0$$

- The **geometrical non-linearity** can be put either : in the **fluid** integration domain or in the **fluid** integrand

ALE formalism : an illustrative example



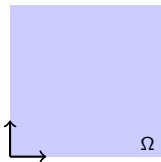
$$\int_{\Omega^f(\boldsymbol{\xi}^S)} \nabla T \cdot \nabla v \, d\mathbf{x} = 0$$

$$\int_{\Omega_0^f} (\mathbf{F}(\boldsymbol{\xi}^S))^{-T} \nabla T \cdot (\mathbf{F}(\boldsymbol{\xi}^S))^{-T} \nabla v \, J(\boldsymbol{\xi}^S) \, d\mathbf{x}_r = 0$$

- The **geometrical non-linearity** can be put either : in the **fluid** integration domain or in the **fluid** integrand
- Imagine what will happen with full Navier-Stokes ...

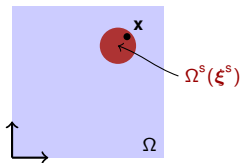
Fictitious Domain formalism : an illustrative example

Current configuration



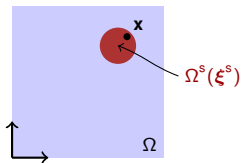
Fictitious Domain formalism : an illustrative example

Current configuration



Fictitious Domain formalism : an illustrative example

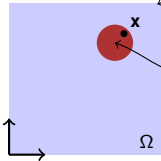
Current configuration



$$\begin{aligned}
 & \underbrace{\int_{\Omega} \nabla T \cdot \nabla v \, d\mathbf{x}}_{\text{physical equation on total domain}} \\
 + & \underbrace{\int_{\Omega^S(\xi^S)} (T - 0) \mu \, d\mathbf{x}}_{\text{constraint}} \\
 + & \underbrace{\int_{\Omega^S(\xi^S)} \lambda v \, d\mathbf{x}}_{\text{Lagrange multiplier}} = 0
 \end{aligned}$$

Fictitious Domain formalism : an illustrative example

Current configuration

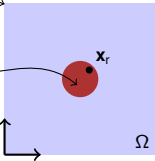


$$\mathbf{x} = \mathbf{x}_r + \boldsymbol{\xi}(\mathbf{x}_r, t)$$

$$\mathbf{F} = \frac{\partial \mathbf{x}}{\partial \mathbf{x}_r}$$

$$J = \det(\mathbf{F})$$

Reference configuration



$$\underbrace{\int_{\Omega} \nabla T \cdot \nabla v \, d\mathbf{x}}_{\text{physical equation on total domain}}$$

+

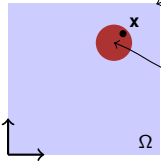
$$\underbrace{\int_{\Omega^S(\boldsymbol{\xi}^S)} (T - 0) \mu \, d\mathbf{x}}_{\text{constraint}}$$

+

$$\underbrace{\int_{\Omega^S(\boldsymbol{\xi}^S)} \lambda v \, d\mathbf{x}}_{\text{Lagrange multiplier}} = 0$$

Fictitious Domain formalism : an illustrative example

Current configuration

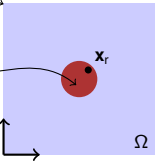


\mathbf{x}

$\Omega^S(\xi^S)$

Ω

Reference configuration



\mathbf{x}_r

Ω_0^S

Ω

$$\mathbf{x} = \mathbf{x}_r + \boldsymbol{\xi}(\mathbf{x}_r, t)$$

$$\mathbf{F} = \frac{\partial \mathbf{x}}{\partial \mathbf{x}_r}$$

$$J = \det(\mathbf{F})$$

$$\underbrace{\int_{\Omega} \nabla T \cdot \nabla v \, d\mathbf{x}}_{\text{physical equation on total domain}}$$

$$+ \underbrace{\int_{\Omega^S(\xi^S)} (T - 0) \mu \, d\mathbf{x}}_{\text{constraint}}$$

$$+ \underbrace{\int_{\Omega^S(\xi^S)} \lambda v \, d\mathbf{x}}_{\text{Lagrange multiplier}} = 0$$

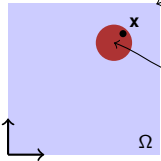
$$\underbrace{\int_{\Omega} \nabla T \cdot \nabla v \, d\mathbf{x}}_{\text{physical equation on total domain}}$$

$$+ \underbrace{\int_{\Omega_0^S} (T(\mathbf{x}_r + \boldsymbol{\xi}^S) - 0) \mu(\mathbf{x}_r + \boldsymbol{\xi}^S) J(\boldsymbol{\xi}^S) d\mathbf{x}_r}_{\text{constraint}}$$

$$+ \underbrace{\int_{\Omega_0^S} \lambda(\mathbf{x}_r + \boldsymbol{\xi}^S) v(\mathbf{x}_r + \boldsymbol{\xi}^S) J(\boldsymbol{\xi}^S) d\mathbf{x}_r}_{\text{Lagrange multiplier}} = 0$$

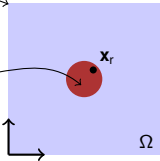
Fictitious Domain formalism : an illustrative example

Current configuration



$\mathbf{x} = \mathbf{x}_r + \boldsymbol{\xi}(\mathbf{x}_r, t)$
 $\mathbf{F} = \frac{\partial \mathbf{x}}{\partial \mathbf{x}_r}$
 $J = \det(\mathbf{F})$

Reference configuration



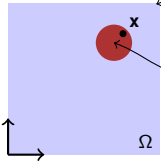
$$\begin{aligned}
 & \underbrace{\int_{\Omega} \nabla T \cdot \nabla v \, d\mathbf{x}}_{\text{physical equation on total domain}} \\
 & + \underbrace{\int_{\Omega^S(\boldsymbol{\xi}^S)} (T - 0) \mu \, d\mathbf{x}}_{\text{constraint}} \\
 & + \underbrace{\int_{\Omega^S(\boldsymbol{\xi}^S)} \lambda v \, d\mathbf{x}}_{\text{Lagrange multiplier}} = 0
 \end{aligned}$$

$$\begin{aligned}
 & \underbrace{\int_{\Omega} \nabla T \cdot \nabla v \, d\mathbf{x}}_{\text{physical equation on total domain}} \\
 & + \underbrace{\int_{\Omega_0^S} (T(\mathbf{x}_r + \boldsymbol{\xi}^S) - 0) \mu(\mathbf{x}_r + \boldsymbol{\xi}^S) J(\boldsymbol{\xi}^S) \, d\mathbf{x}_r}_{\text{constraint}} \\
 & + \underbrace{\int_{\Omega_0^S} \lambda(\mathbf{x}_r + \boldsymbol{\xi}^S) v(\mathbf{x}_r + \boldsymbol{\xi}^S) J(\boldsymbol{\xi}^S) \, d\mathbf{x}_r}_{\text{Lagrange multiplier}} = 0
 \end{aligned}$$

- The **geometrical non-linearity** can be put either : in the **solid** integration domain or in the **solid** integrand

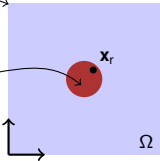
Fictitious Domain formalism : an illustrative example

Current configuration



$\mathbf{x} = \mathbf{x}_r + \boldsymbol{\xi}(\mathbf{x}_r, t)$
 $\mathbf{F} = \frac{\partial \mathbf{x}}{\partial \mathbf{x}_r}$
 $J = \det(\mathbf{F})$

Reference configuration



$$\underbrace{\int_{\Omega} \nabla T \cdot \nabla v \, d\mathbf{x}}_{\text{physical equation on total domain}}$$

$$+ \underbrace{\int_{\Omega^S(\boldsymbol{\xi}^S)} (T - 0) \mu \, d\mathbf{x}}_{\text{constraint}}$$

$$+ \underbrace{\int_{\Omega^S(\boldsymbol{\xi}^S)} \lambda v \, d\mathbf{x}}_{\text{Lagrange multiplier}} = 0$$

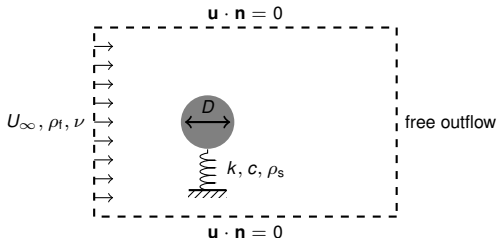
$$\underbrace{\int_{\Omega} \nabla T \cdot \nabla v \, d\mathbf{x}}_{\text{physical equation on total domain}}$$

$$+ \underbrace{\int_{\Omega_0^S} (T(\mathbf{x}_r + \boldsymbol{\xi}^S) - 0) \mu(\mathbf{x}_r + \boldsymbol{\xi}^S) J(\boldsymbol{\xi}^S) \, d\mathbf{x}_r}_{\text{constraint}}$$

$$+ \underbrace{\int_{\Omega_0^S} \lambda(\mathbf{x}_r + \boldsymbol{\xi}^S) v(\mathbf{x}_r + \boldsymbol{\xi}^S) J(\boldsymbol{\xi}^S) \, d\mathbf{x}_r}_{\text{Lagrange multiplier}} = 0$$

- The **geometrical non-linearity** can be put either : in the **solid** integration domain or in the **solid** integrand
- **Nothing different** with the full Navier-Stokes ...

Problem set-up



Modelisation

- **Fluid model** : Navier-Stokes
- **Solid model** : damped linear oscillator

Non-dimensional numbers :

$$Re = \frac{\rho_f U_\infty D}{\nu} = 40$$

$$\omega_0 = \sqrt{\frac{k}{m}} \frac{D}{U_\infty} = 0.8,$$

$$\zeta = \frac{c}{2\sqrt{km}} = 0.01$$

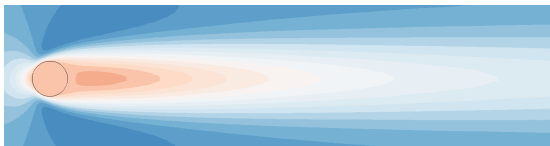
$$\tilde{m} = \frac{\rho_s}{\rho_f} = 10$$

Numerics :

- Finite elements modelisation in Freefem++ (Taylor-Hood elements)
- Newton's method for baseflows calculations
- Shift and invert method for eigenvalue computations with ARPACK

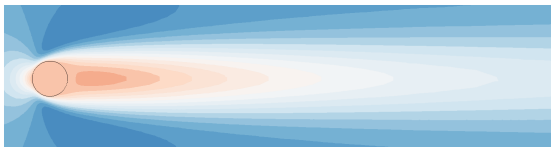
Comparison of stationary fields

Fictitious Domain



Comparison of stationary fields

Fictitious Domain



ALE

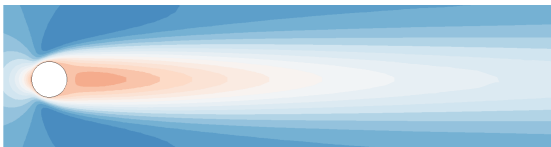
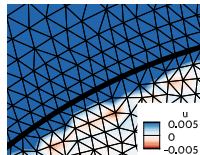
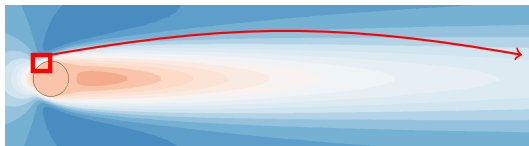


FIGURE – Baseflows : x-velocity

Comparison of stationary fields

Fictitious Domain



ALE

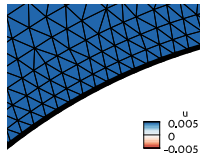
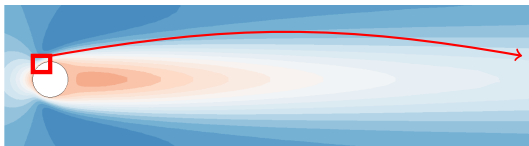
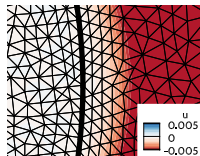
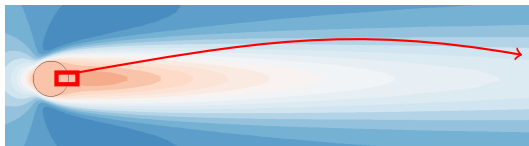


FIGURE – Baseflows : x-velocity

Comparison of stationary fields

Fictitious Domain



ALE

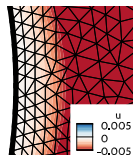
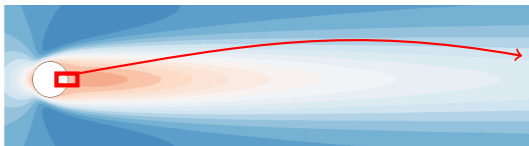
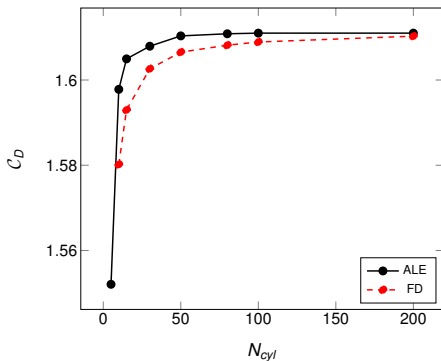


FIGURE – Baseflows : x-velocity

Comparison of stationary fields



- FD converges towards ALE value when refining on the solid walls
- Excellent comparison of converged C_D values

Eigenvalue problem : comparison of spectrums

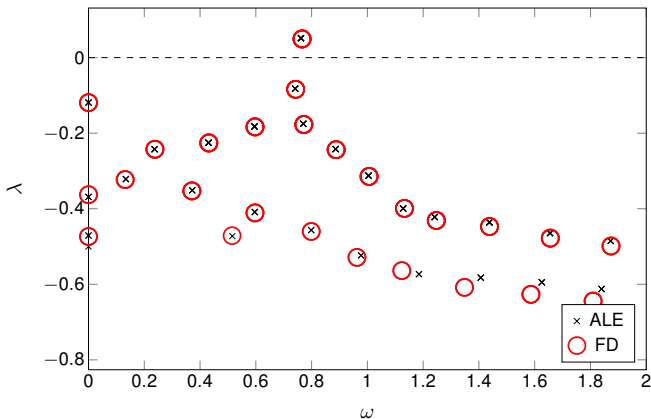
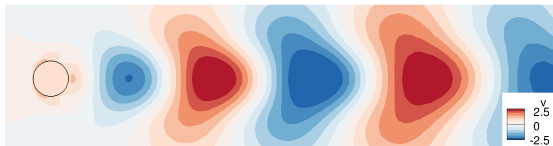


FIGURE – Spectrums

- FD and ALE spectrums are similar

Comparison of eigenmodes

Fictitious Domain



Comparison of eigenmodes

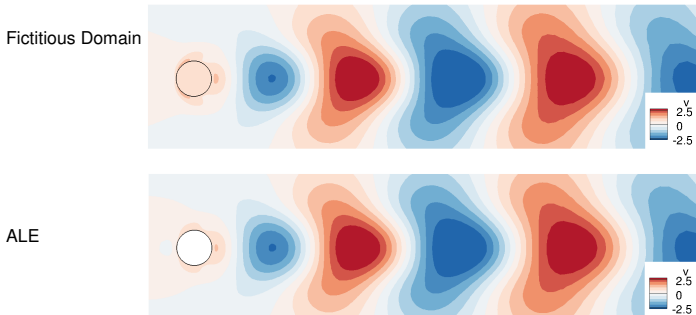
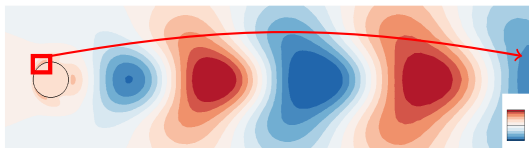


FIGURE – Eigenmodes : x-velocity

Comparison of eigenmodes

Fictitious Domain



ALE

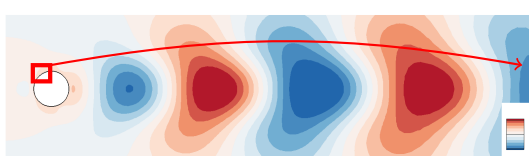


FIGURE – Eigenmodes : x-velocity

Comparison of eigenmodes

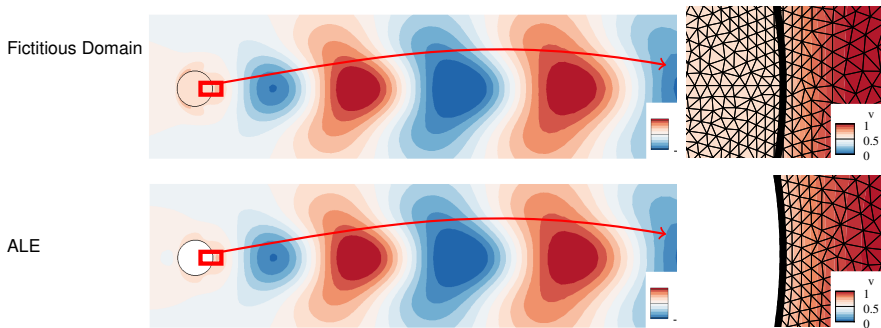
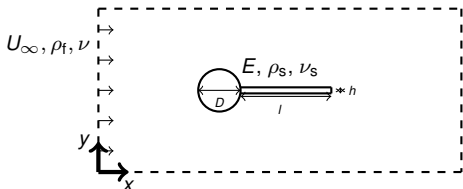


FIGURE – Eigenmodes : y-velocity

Problem set-up

Geometry



Modelisation

- Fluid model : Navier-Stokes
- Solid model : linear elasticity

Non-dimensional numbers :

$$Re = \frac{\rho_f U_\infty D}{\mu} = 100$$

$$K_b = \frac{\nu_f}{12 \rho_f U_\infty^2 \beta} = 0.04, \nu_s = 0.35,$$

$$\frac{h}{l} = 0.03$$

$$\tilde{m} = \frac{\rho_s}{\rho_f} = 85$$

Numerics :

- Finite elements modelisation in Freefem++ (Taylor-Hood elements)
- Newton's method for baseflows calculations
- Shift and invert method for eigenvalue computations with ARPACK

Comparison of stationary fields

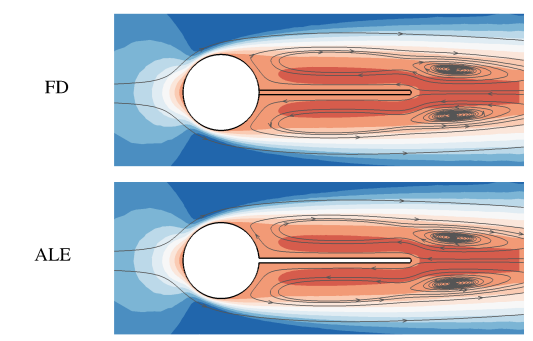


FIGURE – Stationary solution : ALE vs FD

Comparison of stationary fields

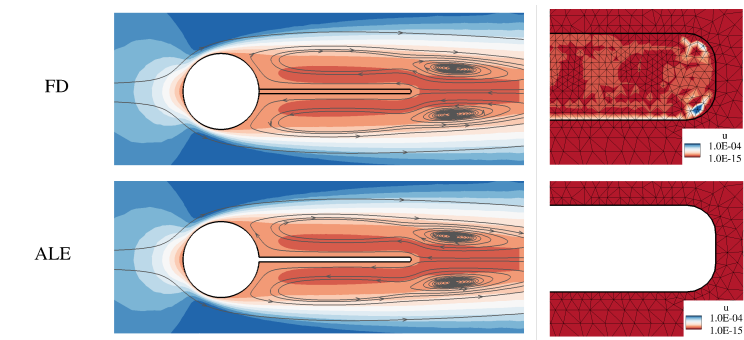
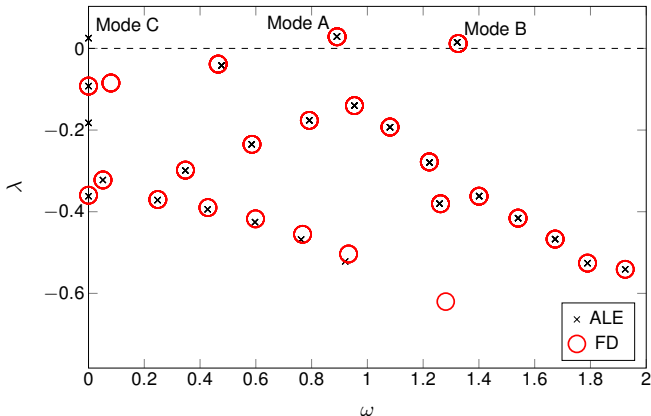


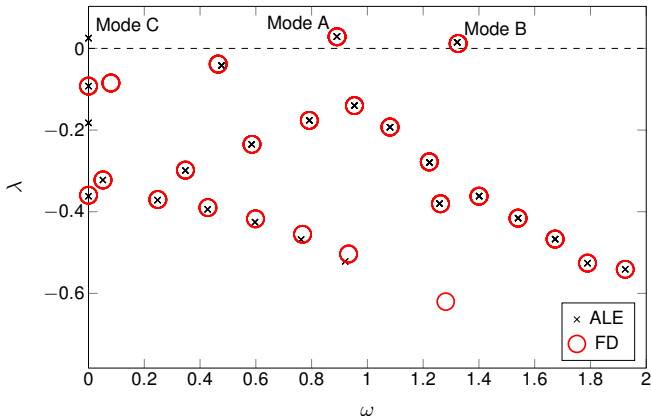
FIGURE – Stationary solution : ALE vs FD

Eigenvalue problem : comparison of spectrums



- FD and ALE spectrums are similar ...

Eigenvalue problem : comparison of spectrums



- FD and ALE spectrums are similar ...
- ... **Except** from the unstable steady mode C

Comparison of eigenmodes

Unstable unsteady modes

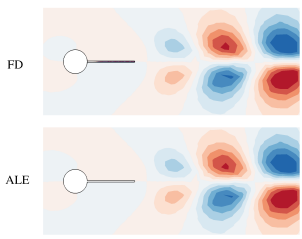


FIGURE – Mode A : pressure distribution

➔ VIV instability

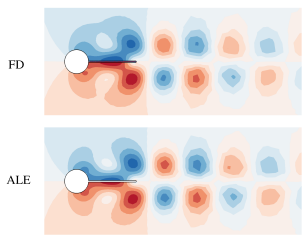


FIGURE – Mode B : pressure distribution

➔ Mix flutter-VIV instability

What about the steady mode ?

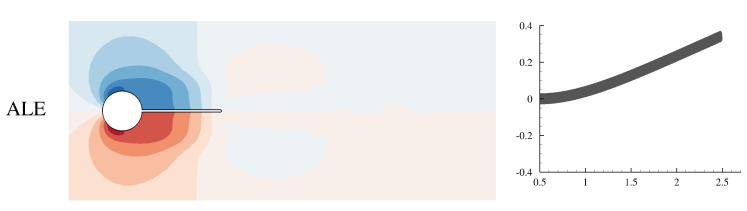


FIGURE – Mode C : pressure distribution

What about the steady mode ?

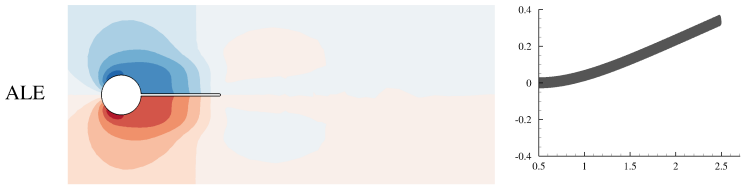


FIGURE – Mode C : pressure distribution

➔ Aeroelastic divergence instability

What about the steady mode ?

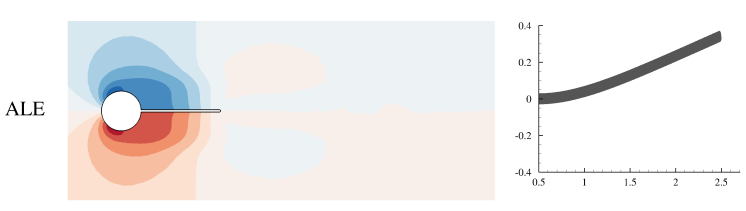


FIGURE – Mode C : pressure distribution

- ➔ Aeroelastic divergence instability
 - added stiffness due to the fluid forces

Conclusion

Present work

- We discussed the use of a **Fictitious Domain** framework for **linear stability analysis of FSI** problems
- The **Fictitious Domain** predicts **accurate baseflows and eigenvalue spectrums** in most of our test cases at **lower computational cost** (7-10 times faster)
- Its precision is still in question for some types of instabilities where the interface stresses need particularly accurate evaluation

Perspectives

- **Other types of FSI instabilities** should be tested (wing flutter, galloping)
- The use of **more recent non-conformal methods** might be considered